

# TMP-F200 Series OEM Laser Rangefinder Module

# 1. INTRODUCTION

This data sheet describes a rugged, compact OEM laser rangefinder (LRF) module based on a patented Precision Distance Measurement (PDM) technology and designed for integration into customer's systems.



# **Applications**

- Homeland Security
- Civil engineering
- · Automotive & industrial metrology
- Object tracking

# **Features**

- Cost effective LRF solution
- Eye safe 1550nm wavelength
- Rugged O-ring sealed enclosure
- Automatic trade off between range precision measurement rate
  - ☐ Operating range 20m-9Km+
  - ☐ Precision 0.1-10m
- First/Last Range Logic





#### **Options**

- · Chassis versions for OEM's
- · Vehicle power supply filtering
- Ruggedisation for vehicle applications
- Integrated CCD Camera
- RS422 control interface
- Starter kits
- · Weaver rail and telescope kits

# 2. DESCRIPTION

The LRF is manufactured from a precision machined aluminium chassis with O-ring sealed outer case optimised for stable operation over the wide temperature range experienced in homeland security and other demanding applications.

A laser diode and associated optical system generates a sequence of laser pulses which are transmitted to the object being measured. The reflected pulses are detected by the receiving optical system which focuses the light onto a high performance InGaAs detector. The detector output is amplified, digitised and then processed using a novel DSP algorithms to calculate the distance to the object.

For any LRF, there is a trade off between the signal to noise ratio of the received signal; precision of the range measurement; maximum range; and energy and time required to make the measurement. The patented digital signal processing based technology allows the trade-off between these factors to be optimised. As standard the LRF operates in an autonomous mode, adapting the measurement time to the strength of the returned signal and using the signal to noise ratio to optimum effect so that for objects at shorter ranges, the measurement precision is enhanced. Alternative trade-offs can be provided to suit different applications and we would be pleased to discuss these.

## 3. OPTIONS

The following options are available or planned.

#### 3.1 Chassis Version

For those customer's wishing to integrate the LRF200 Series within their own housing, the LRF200 Series can be supplied in an open frame configuration without the rear case or rear connector.

#### 3.2 Vehicle Power Supply Filtering

To allow the LRF200 Series to be powered directly from a vehicle supply, an additional filter can be integrated into the case, to protect the LRF against the transients and surges normally experienced with such a supply. The filter is MIL-1275 compatible.

#### 3.3 Vehicle Ruggedisation

The LRF200 Series in its basic form is compact and rugged unit. However, for those applications where sustained, high levels of shock and vibration are expected a ruggedisation option is available in which the larger components such as capacitors and inductors are glued or tied to the printed circuit board. This option is relevant for applications such as off-road surveillance vehicles and police or customs helicopters.

# 3.4 Integrated CCD Camera/Graticule Generator

The LRF200 Series is available with an integrated CCD camera, which views the scene via the LRF receiver lens and optical channel which incorporates a beam splitter to allow the LRF detector and CCD camera to operate simultaneously.

The CCD camera can either be used as a narrow field of view camera for scene observation or, in conjunction with the optional graticule generator, to allow boresighting of the LRF with other sensors: for example, night vision cameras. The CCD camera continues to operate whilst the LRF is firing, without disruption of the video signal. This is particularly useful when a video auto-tracker is used to keep the LRF

line of sight aligned on moving objects, or where the video is being recorded for evidential purposes.



So far we have supplied the LRF with a monochrome camera, but would be able to supply colour if required. Please contact the factory for more details.

#### 3.5 RS422 control interface

As an alternative to the standard RS232 control interface, we can supply the LRF with an RS422 interface for greater noise immunity.



#### 3.6 Starter Kit

To allow customers to get the LRF up and running quickly, we offer a starter kit comprising Windows XP™ compatible control software, a power/data cable and a universal mains power supply module. The software allows the operator to set the minimum and maximum range gates; fire the LRF; display the first and last range measurements and put the unit into standby and sleep modes.

#### 3.7 Weaver Rail and Telescope Kits

A Weaver rail kit can be fitted to the top of the LRF case to allow additional optical instruments to be attached to the LRF. An optional 6X optical sight is offered as an option to fit to the Weaver rail. The photograph to the left shows the Weaver rail and telescope fitted to the LRF.



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## 4. OUTLINE TECHNICAL SPECIFICATION

Configuration	Open frame chassis version	Sealed version			
Weight:	0.89kg approx	1.24kg approx			
Dimensions and mechanical interface	Please refer to the outline drawing				
Mechanical interface:	Tapped mounting points on the base and front of the unit.  Please refer to the outline drawing				
Specified range:	5Km with ≥10Km visibility, for a 2.3m x 2.3m target with a reflectivity of 30% and a measurement time of 1.0 seconds				
Maximum range	>9Km under the best conditions, with extended measurement time				
Minimum range	20m				
Range Resolution	1m (Option: 0.1m)				
Range Accuracy	5m 1σ (Option: 2m 1σ)				
Multiple object capability	First/Last reflections are returned				
Wavelength:	1550nm (nominal)				
Beam Divergence:	0.6 mrad (Horizontal) x 0.4 mrad (Vertical) nominal				
Beam Dimensions:	50mm (Horizontal) x 10 mm (Vertical) nominal at laser exit optic				
Data Connections:	External computer RS232 (RS422 option)				
Eye Safety:	Class 1M Eye Safe				
Environmental:	Lenses are sealed to front face of LRF, rear is open	IP67 Sealing			
	-30° to +50° Ambient Air Operating temperature				
Power Supply:	10 -30∨dc, ripple<100m∨pp				
Power consumption:	Peak power <26 Watts whilst the laser is firing				
	Idle Power: 2.6 Watts				
	Sleep Power: 0.4W				

The above figures are provision ratings and assume typical applications. Actual performance will depend on many parameters including configuration and environmental conditions

#### 5. LASER SAFETY

Laser safety guidelines documents are available on request.

#### 6. INTERFACES

#### 6.1 Mechanical interface

Please refer to the outline drawing.

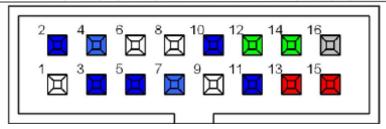
#### 6.2 Communication interface

The LRF module is controlled by means of a serial communications link complying with TIA/EIA RS-232. Please refer to Communications protocol document available on request.

#### 6.3 Electrical interface- Chassis version

The unit is fitted with a MOLEX 87831-1620 16 way PCB mounted connector which is designed to mate with a cable mounted MOLEX 51110-1651 16 way connector.





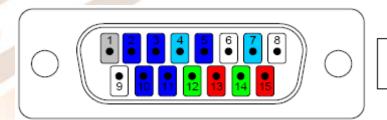
PCB Connector (Viewed face on)

# 6.3.1 Power & Comms PCB mounted connector pin out detail (CONN 3)

Pin	Description	Group	Function	Notes
15	LRF_Driver_Power	Power	Power supply input to the laser driver circuit. This is separated from the LRF system power to enable external electrical interlock to be implemented for laser safety.	-
13	LRF_Power		Power supply to the LRF system, excluding the laser driver.	-
14	LRF_Driver_Power_0V	Power Return	Power supply input to the laser driver circuit.  This is separated from the LRF system power to enable external electrical interlock to be implemented for laser safety.	-
12	LRF_Power_0V		Power supply to the LRF system, excluding the laser driver.	-
2	Reserved		Reserved	-
3	RS 232 RX	RS 232 data input pair		-
10	RS 232 TX	Comms	Comms RS 232 data output pair	
11	Reserved		Reserved	-
5	RS Shield		RS Shield	-
4	Reserved	Prog	In circuit programming	Instro use only
7	Reserved	Flog	In circuit Programming	Instro use only
16	Chassis GND	GND	Connected to LRF Chassis	-
1	No Connect		-	-
6	No Connect	-		
8	No Connect			
9	No Connect	-	-	-

# 6.4 Electrical interface- Chassis version via adapter cable

The unit can be fitted with an adapter cable, supplied as part of the Starter Kit. The adapter cable is fitted with a AMPLIMITE HD20 / 15 Way D-Type PLUG 747908-2 which is designed to mate with a AMPLIMITE HD20 / 15 Way D-Type SOCKET 747909-2. The opposite end of the adapter cable is designed to mate with the power & communications PCB connector (shown on the previous page).



D Type Connector (Viewed face on)

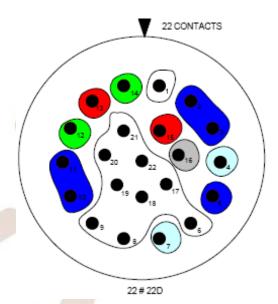
# 6.4.1 Power & Comms Adapter Cable Connector Pin-Out Detail

Pin	Description	Group	Function	Notes
15	LRF_Driver_Power	Power	Power supply input to the laser driver circuit. This is separated from the LRF system power to enable external electrical interlock to be implemented for laser safety.	-
13	LRF_Power		Power supply to the LRF system, excluding the laser driver.	-
14	LRF_Driver_Power_0V	Power Return	Power supply input to the laser driver circuit. This is separated from the LRF system power to enable external electrical interlock to be implemented for laser safety.	-
12	LRF_Power_0V		Power supply to the LRF system, excluding the laser driver.	-
2	RS 232 TX		RS 232 data output pair	-
3 10	RS 232 RX Reserved	Comms	RS 232 data input pair Reserved	-
11 5	Reserved RS Shield		Reserved RS Shield	-
4	Reserved	Prog	In circuit programming	Instro use only
7	Reserved		In circuit Programming	Instro use only
1	Chassis GND	GND	Connected to LRF Chassis	-
6	No Connect	-	-	-
8 9	No Connect No Connect	-	-	-

# 6.5 Electrical interface- Enclosed version

☐ LRF Connector- Mil-C-D38999-24-WC-35-PN

□ Mates with- Mil-C-D38999-26-WC-35-SN





# 6.5.1 Connector pin out detail

Pin	Description	Group	Function	Notes
15	LRF_Driver_Power	Power	Power supply input to the laser driver circuit. This is separated from the LRF system power to enable external electrical interlock to be implemented for laser safety.	-
13	LRF_Power		Power supply to the LRF system, excluding the laser driver.	-
14	LRF_Driver_Power_0V	Power Return	Power supply input to the laser driver circuit. This is separated from the LRF system power to enable external electrical interlock to be implemented for laser safety.	-
12	LRF_Power_0V	Ketaiii	Power supply to the LRF system, excluding the laser driver.	-
2	RS 232 TX		RS232 data output pair	-
3	RS 232 RX		RS232 data input pair	-
10	Reserved	Comms	Reserved	-
11	Reserved		Reserved	-
5	RS Shield		RS Shield	-
4	Reserved	Prog	In circuit programming	Instro use only
7	Reserved	Prog	In circuit Programming	Instro use only
16	Chassis Ground	GND	Connected to LRF Chassis	-
1, 6, 8, 9, 17-22	No Connect	-	-	-